

Bosch Metadata and IVA Events in ONVIF

Analytic Events, Metadata and MIC 9000





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Revision History

Version / Issue	Date	Editor / Author	Description of Change
1.1	4.March.21	Hafizoglu Huseyin Tughan (BT- VS/MKI)	Updated document dates.
1.0	06.June.16	Eichhorn Andre (BT- VS/MKI)	First official release of Bosch Metadata and Analytics Events in ONVIF

1 Scope

This document describes the usage of the Bosch edge Intelligent Video analysis (IVA) via the standard interface ONVIF. With ONVIF (Bosch FW 6.10 and higher) it is supported to receive Analysis Events based on the IVA rule engine on the edge and the metadata stream in the ONVIF format.

Further information on the Bosch IVA: <u>http://www.boschsecurity.com/hdsecurity/Default.aspx?language=en&tab=inteligent-video-analysis</u>

2 IVA Events via ONVIF

IVA Events via ONVIF are based on the IVA rule engine of the Bosch camera on the edge, the Bosch device supports up to eight IVA rules. The configuration of the rules needs to be done on the webpage of the device.

2.1 List of Supported IVA rules

- Object In Field
- Crossing Line
- Loitering
- Condition Change
- Following Route
- Removed Object
- Idle Object
- Entering Field
- Leaving Field
- Similarity Search
- Crowd Detection
- Counter (Alarm)

Supported Analytic AVIOTEC IP starlight 8000 (only available with this camera Model)

- Fire Alarm
- Smoke Alarm

ONVIF IVA event message contains the video source the event type and the rule name (see screenshot on page 3). All IVA events are part of the ONVIF request *GetEventProperties*, furthermore it is supported to dynamically create new IVA rules. In case a new IVA rule is created on the camera the *GetEventProperties* needs to request it by the ONVIF client again. Changes of created rules (eg. moving a crossing line etc.) do not require an update of the *GetEventProperties*.

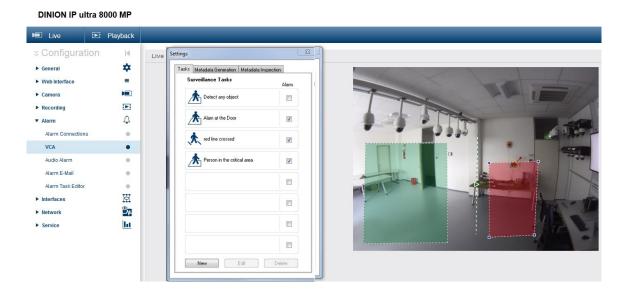
Note: To be backward compatible all IVA events are transmitted as motion alarm event, too.

Example of IVA Event Messages:

Bosch		Events					
	Identification	⊘ Filters					
	Time settings Maintenance	Arrival time	Topic	Operation	Source	Key Data	
-	Network settings	13:58:12	tns1:IVA/ObjectInField/Person_in_critical_area_one	Initialized	VideoSourceToken: 1	State: false	
	User management	13:58:12	tns1:IVA/CrossingLine/Man_crossed_the_line	Initialized	VideoSourceToken: 1	State: false	
	Certificates	13:58:12	tns1:IVA/ObjectInField/critical_area_two	Initialized	VideoSourceToken: 1	State: false	
	Relays	13:58:12	tns1:VideoSource/MotionAlarm	Initialized	VideoSourceToken: 1	State: true	
	Web page	13:58:12	tns1:VideoSource/SignalLoss	Initialized	VideoSourceToken: 1	State: false	
	Events	13:58:12	tns1:Device/Trigger/Relay	Initialized	RelayToken: 1	LogicalState: inactive	
IVT	Refresh	13:58:12	tns1:Device/Trigger/DigitalInput	Initialized	InputToken: 1	LogicalState: false	
111	Kerresh	13:58:12	tns1:Device/Trigger/DigitalInput	Initialized	InputToken: 2	LogicalState: false	
1: H264_L151		13:58:17	tns1:IVA/ObjectInField/critical_area_two	Changed	VideoSourceToken: 1	State: false	
	Live video	13:58:17	tns1:VideoSource/MotionAlarm	Changed	VideoSourceToken: 1	State: false	
15 15 PM	Video streaming	13:58:22	tns1:IVA/ObjectInField/critical_area_two	Changed	VideoSourceToken 1	State: true	
A PURE DOM	Imaging settings	13:58:22	tns /ideoSource/MotionAlarr	Changed	VideoSourceToken: 1	Stat	
111 1 1 1 1	Profiles	13:58:40	Ins1:IVA/ObjectInField/critical_area_two	Changed	VideoSourceToken: 1	State false	
And		13:58:40	tns1:VideoSource/MotionAlarm	Changed	VideoSou ceToken: 1	State false	
6		13:58:41	tns1:IVA/ObjectinField/critical_area_two	Changed	VideoSourceToken: 1	State true	
		13 38:41	tns1:VideoSource/MotionAlarm	Changed	VideoSou ceToken: 1	State true	
	Analy	sisstype	tns1:IVA/ObjectInField/criti	Changed	VideoSourceToken: 1	Status	
	Andry	13:58:42	tns1:VideoSource/MotionAlarm	Changed	VideoSourceToken: 1	State: false	
		13:58:45	tos1:IVA/ObjectInField/critical_area_two	Changed	VideoSourceToken: 1	State: true	
		13:58:45	EVenturdy pealarm	Change IC	eo Source	State: true	
		13:58:49	tns1:IVA/ObjectInField/Person_in_critical_area_one	Changed	VideoSourceToken: 1	State: true	
		13:58:51	tns1:IVA/CrossingLine/Man_crossed_the_line	Changed	VideoSourceToken: 1	State: true	
		13:58:52	tns1:IVA/ObjectInField/Person_in_critical_area_one	Changed	VideoSourceToken: 1	State: false	
		13:58:52	tns1:IVA/CrossingLine/Man_crossed_the_line	Changed	VideoSourceToken: 1	State: false	
		13:58:57	tns1:IVA/ObjectInField/Person_in_critical_area_one	Changed	VideoSourceToken: 1	State: true	
		13:59:01	tns1:IVA/ObjectInField/Person_in_critical_area_one	Changed	VideoSourceToken: 1	State: false	
		13:59:02	tns1:IVA/ObjectInField/critical_area_two	Changed	VideoSourceToken: 1	State: false	

2.2 Configuration of OVA rules via the camera website

Camera webpage => Settings => Alarm => VCA => Configuration



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3 ONVIF Metadata

3.1 Onvif Metadata Features coverage FW 6.50 an newer

- Object coordinates
- Center of Gravity
- Object ID

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- Polygon points
- Bounding box coordinates
- Polygon points
- Geolocation information of Objects
- velocity of the objects in [m/s] *
- area/size information in [qm] *
 - Class candidate *
 - o Class;
 - Human
 - Face
 - Vehicle'
 - Other
 - Extension (more details)
 - Head
 - Group
 - SmallObject
 - Fire
 - Smoke
 - Car
 - Bike
 - Truck
- Other
 counter as an event (only in the metadata stream)
- Event to Object mapping
 - The events show the object ID of the object, which triggered the event
- Source information (line) of object for MIC fusion 9000

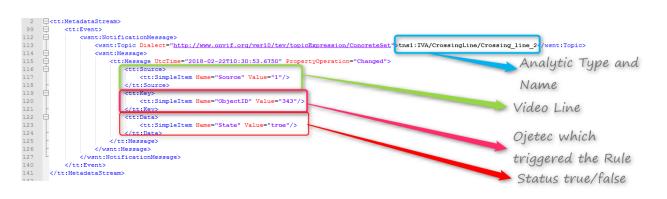
*Camera needs to be calibrated via website or Bosch tools

Note: The ONVIF Metadata (MetadataConfig1) must be added manually to the ONVIF profile **Note**: Due error in the ONVIF Metadata Spec 'Vehicle' is signaled as 'Vehical'

3.2 Example of the ONVIF Metadata stream:

<pre>tt:Metadat <tt:vid< pre=""></tt:vid<></pre>	leoAnalytics>	> ObjectId
	<pre>::Frame UtcTime="2018_02_22T10:30:51.48510"></pre>	
	<tt:appearance area="252.61" velocity="13.23"></tt:appearance>	velocity and Object siz
F	<tt:shope: <tt:boundingbox bottom="-0.52" left="-0.6</th><th>so" right="-0.07" top="-0.23"></tt:boundingbox> Pau di a Pau</tt:shope: 	
	<tt:centerofgravity v="-0.37" x="-0.33"></tt:centerofgravity>	Bounding Box
户	<tt:polygon></tt:polygon>	
	<pre><tt:point x="-0.57" y="-0.48"></tt:point> <tt:point x="-0.54" y="-0.48"></tt:point></pre>	
	<tt:point x="-0.51" y="-0.47"></tt:point>	
	<tt:point x="-0.47" y="-0.47"></tt:point>	- 55
	<tt:point x="-0.44" y="-0.46"></tt:point>	
	<tt:point x="-0.41" y="-0.45"></tt:point> <tt:point x="-0.37" y="-0.45"></tt:point>	
	<tt:point x="-0.34" y="-0.43"></tt:point>	
	<tt:point x="-0.31" y="-0.43"></tt:point>	
	<tt:point x="-0.28" y="-0.43"></tt:point> <tt:point x="-0.24" y="-0.43"></tt:point>	
	<tt:point x="-0.24" y="-0.45"></tt:point> <tt:point x="-0.21" y="-0.44"></tt:point>	
	<tt:point x="-0.18" y="-0.44"></tt:point>	
	<tt:point x="-0.14" y="-0.43"></tt:point>	
	<tt:point x="-0.11" y="-0.43"></tt:point> <tt:point x="-0.08" y="-0.42"></tt:point>	
	<tt:point x="-0.07" y="-0.41"></tt:point>	
	<tt:point x="-0.07" y="-0.38"></tt:point>	
	<tt:point x="-0.06" y="-0.37"></tt:point>	
	<tt:point x="-0.06" y="-0.35"></tt:point> <tt:point x="-0.06" y="-0.33"></tt:point>	
	<tt:point x="-0.07" y="-0.31"></tt:point>	
	<tt:point x="-0.08" y="-0.30"></tt:point>	
	<tt:point x="-0.08" y="-0.26"></tt:point> <tt:point x="-0.11" y="-0.23"></tt:point>	
	<tt:point x="-0.14" y="-0.23"></tt:point>	
	<tt:point x="-0.18" y="-0.23"></tt:point>	
	<tt:point x="-0.21" y="-0.24"></tt:point>	
	<tt:point x="-0.24" y="-0.25"></tt:point> <tt:point x="-0.28" y="-0.25"></tt:point>	
	<tt:point x="-0.31" y="-0.28"></tt:point>	
	<tt:point x="-0.34" y="-0.31"></tt:point>	
	<tt:point x="-0.37" y="-0.33"></tt:point>	
	<tt:point x="-0.41" y="-0.35"></tt:point> <tt:point x="-0.44" y="-0.35"></tt:point>	
	<tt:point x="-0.47" y="-0.35"></tt:point>	
	<tt:point x="-0.51" y="-0.35"></tt:point>	
	<tt:point v="-0.34" x="-0.54"></tt:point>	
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¢.	<tt:class></tt:class>	
户	<tt:classcandidate></tt:classcandidate>	
	<tt:type>Vehical</tt:type> <tt:likelihood>87.00</tt:likelihood>	
-		
<u>É</u>	<tt:extension></tt:extension>	→ Object Type
₽ III	<tt:othertypes></tt:othertypes>	e ejece , gpe
	<tt:type>Car</tt:type> <tt:likelihood>87.00</tt:likelihood>	
-		
	V/ULEXUENSION/	
	 <tt:geolocation elevation="0.00" lat="11.0806473" lon="49.4698867"></tt:geolocation>	Geolocation
-		51001000010101
	:t:Frame> .deoAnalytics>	
	Accountly Lics>	

3.3 Example of the ONVIF Metadata stream Event to Object Mapping

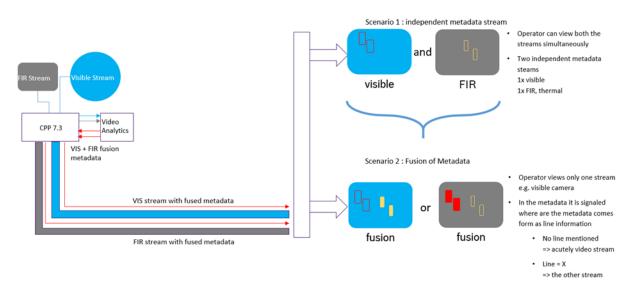


4 MIC fusion 9000

The Bosch MIC fusion contains a visible and a thermal camera and provides fusion of the Metadata of both cameras.

MIC IP fusion 9000i

Concept: Fusion of Metadata from both camera streams



It is supported to use the MIC fusion in two modes (fusion mode needs to be disabled on camera)

1. Two channel device with two separate metadata streams The camera behaves like a normal multi-channel device with two independent video and metadata streams

2. Fusion of visible and thermal metadata information

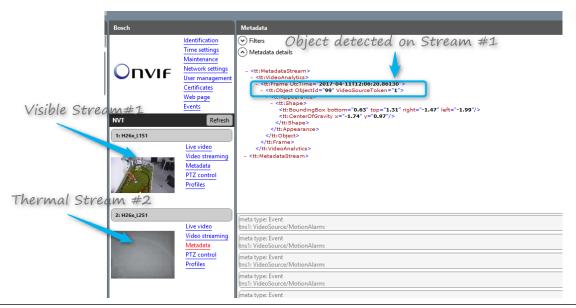
the camera fuses (merges) the two metadata steams into one, with this, the operator can get the thermal metadata information in the visible video and the other way around. The source information of the origin of the object is part of the ONVIE metadata object information and indicated

The source information of the origin of the object is part of the ONVIF metadata object information and indicated like this:

- a. None line information => Object was detected in the currently viewed stream
- b. Object line 'X '=> Object was detected on the other stream number X

Example:

The thermal stream is viewed (stream #2) and an object is detected in the visible stream (stream #1).



5 Appendix

5.1 Featureset on older FWs

With FW 6.10 and higher it is possible to receive metadata in the ONVIF format from Bosch cameras. The metadata contain following information for the bounding Boxes:

- Object coordinates
- Center of Gravity
- Object ID

With FW 6.40 the ONVIF Metadata support is extended by:

- Polygon points
- Class candidate *
 - o Human
 - o Car
 - o Truck
 - o Bike
- Likelihood
- Bounding box coordinates for AVIOTEC camera (Fire/Smoke)
- Source information (line) of object for MIC fusion 9000

With FW 6.50 the ONVIF Metadata support is extended by:

- Geolocation information of Objects
- velocity of the objects in [m/s] *
- area/size information in [qm] *
- Class candidate *
 - Class;
 - Human
 - Face
 - Vehicle'
 - Other
 - Extension (more details)
 - Head
 - Group
 - SmallObject
 - Fire
 - Smoke
 - Car
 - Bike
 - Truck
 - Other
- counter as an event (only in the metadata stream)
- Event to Object mapping

The events show the object ID of the object, which triggered the event

5.2 GetEventProperties Description

2. GetEventProperties

Description:

The WS-BaseNotification specification defines a set of OPTIONAL WS-ResouceProperties. This specification does not require the implementation of the WS-ResourceProperty interface. Instead, the subsequent direct interface shall be implemented by an ONVIF compliant device in order to provide information about the FilterDialects, Schema files and topics supported by the device.

SOAP action:

http://www.onvif.org/ver10/events/wsdl/EventPortType/GetEventPropertiesRequest

Input:

[GetEventProperties]

Output:

[GetEventPropertiesResponse]

TopicNamespaceLocation - unbounded; [anyURI]
List of topic namespaces supported

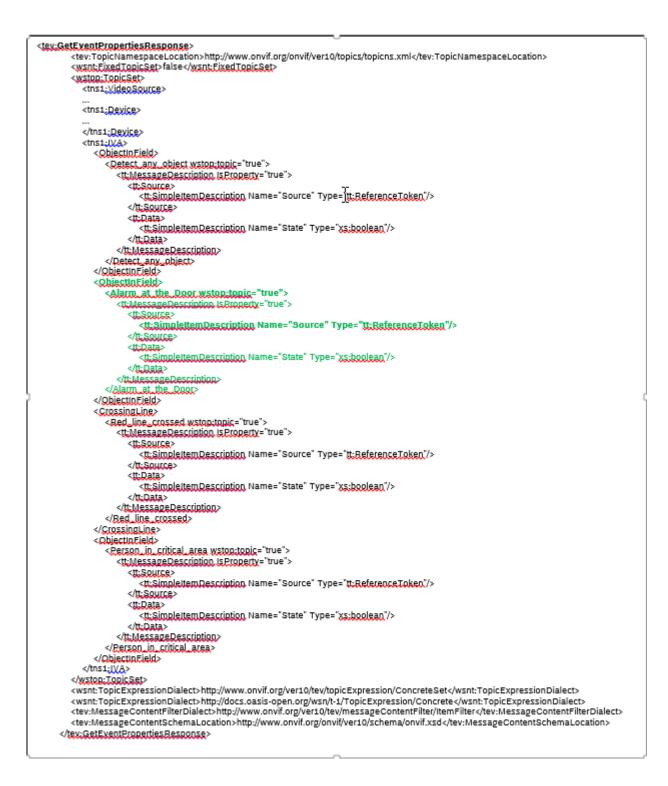
List of topic namespaces supported. FixedTopicSet [FixedTopicSet] True when topicSets is fixed for all times. TopicSet [TopicSet] Set of topic supported. TopicExpressionDialect - unbounded; [TopicExpressionDialect] Defines the XPath expression syntax supported for matching topic expressions.

- The following TopicExpressionDialects are mandatory for an ONVIF compliant device :
 - http://docs.oasis-open.org/wsn/t-1/TopicExpression/Concrete
 http://www.onvif.org/ver10/tev/topicExpression/ConcreteSet.
- MessageContentFilterDialect unbounded; [anyURI]
- PressageContentrated Data to inbuilded, [anyOA]
 Defines the XPath function set supported for message content filtering.
 The following MessageContentFilterDialects should be returned if a device supports the message content filtering:

 http://www.onvif.org/ver10/tev/messageContentFilter/ItemFilter.
 http://www.onvif.org/ver10/tev/messageContentFilter/ItemFilter.
- A device that does not support any MessageContentFilterDialect returns a single empty url.
 ProducerPropertiesFilterDialect optional, unbounded; [anyURI]
- Optional ProducerPropertiesDialects. Refer to <u>Web Services Base Notification 1.3 (WS-BaseNotification</u>) for advanced filtering. • MessageContentSchemaLocation - unbounded; [anyURI]
- The Message Content Description Language allows referencing of vendor-specific types. In order to ease the integration of such types into a client application, the GetEventPropertiesResponse shall list all URI locations to schema files whose types are used in the description of notifications, with MessageContentSchemaLocation elements.
- This list shall at least contain the URI of the ONVIF schema file. • xsd:any

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5.3 Example of GetEventPropertiesResponse of IVA event



5.4 Add Metadata configuration to ONVIF profile

Bosch		Profiles
Οηνιε	Identification Time settings Maintenance Network settings User management Certificates Relays Web page Events	H264_L1S1 Details : H264_L1S2 Image: Start view expanded JPEG_L1S3 Image: H264_L1S1 token: 0 fixed: False Image: Video Source Configuration: DINION IP ultra 8000 MP Image: Video Encoder Configuration: 12MP Balanced
NVT	Refresh	O Metadata Configuration: MetadataConfig1
1: H264_L151	Live video Video streaming Imaging settings Metadata Profiles	Create Delete Edit Select

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